

Dual-Channel Synchronous DC-DC Step-Down Controller with 5V/3.3V LDOs

General Description

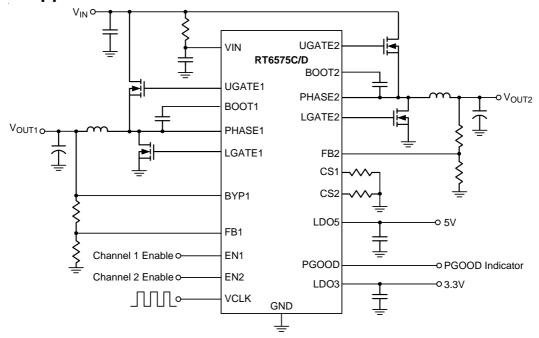
The RT6575C/D is a dual-channel step-down controller generating supply voltages for battery-powered systems. It includes two Pulse-Width Modulation (PWM) controllers adjustable from 2V to 5.5V, and two fixed 5V/3.3V linear regulators. Each linear regulator provides up to 100mA output current and 3.3V linear regulator provides 1% accuracy under 35mA. The RT6575C/D has an oscillator output to drive the external charge pump application. Other features include on-board power-up sequencing, a powergood output, internal soft-start, and soft-discharge output that prevents negative voltage during shutdown.

A constant current ripple PWM control scheme operates without sense resistors and provides 100ns response to load transient. For maximizing power efficiency, the RT6575C/D automatically switches to the diode-emulation mode in light load applications. To eliminate noise in audio applications, an audio-skipping mode is included, which maintains the switching frequency above 25kHz. The RT6575C/D is available in the WQFN-20L 3x3 package.

Features

- Support Connected Standby Mode for Ultrabook
- CCRCOT Control with 100ns Load Step Response
- PWM Maximum Duty Ratio > 98%
- 5V to 25V Input Voltage Range
- Dual Adjustable Output:
 - ► CH1: 2V to 5.5V ► CH2: 2V to 4V
- 5V/3.3V LDOs with 100mA Output Current
- 1% Accuracy on 3.3V LDO Output
- Oscillator Driving Output for Charge Pump Application
- Support Audio-Skipping Mode (ASM)
- Internal Frequency Setting
- → 300kHz/355kHz (CH1/CH2)
- Internal Soft-Start and Soft-Discharge
- 4700ppm/°C R_{DS(ON)} Current Sensing
- Independent Switcher Enable Control
- Built-in OVP/UVP/OCP/OTP
- Non-Latch UVLO
- Power Good Indicator

Simplified Application Circuit

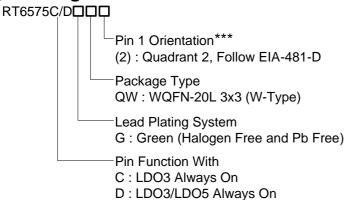




Applications

- Notebook and Sub-Notebook Computers
- System Power Supplies
- 2-Cell to 4-Cell Li+ Battery-Powered Devices

Ordering Information



Note:

***Empty means Pin1 orientation is Quadrant 1

Richtek products are:

- > RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- ▶ Suitable for use in SnPb or Pb-free soldering processes.

Marking Information

RT6575CGQW



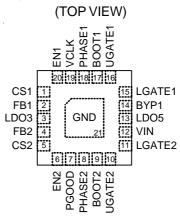
5Y=: Product Code YMDNN: Date Code

RT6575DGQW



5X=: Product Code YMDNN: Date Code

Pin Configurations



WQFN-20L 3x3

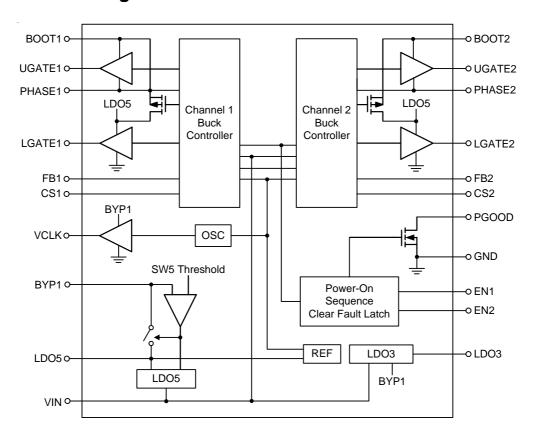


Functional Pin Description

Pin No.	Pin Name	Pin Function
1	CS1	Current Limit Setting. Connect a resistor to GND to set the threshold for Channel 1 synchronous $R_{DS(ON)}$ sense. The GND – PHASE1 current limit threshold is 1/8th the voltage seen at CS1 over a 0.2V to 2V range. There is an internal $10\mu A$ current source from LDO5 to CS1.
2	FB1	Feedback Voltage Input for Channel 1. Connect FB1 to a resistive voltage divider from VOUT1 to GND to adjust output from 2V to 5.5V.
3	LDO3	3.3V Linear Regulator Output. It is always on when VIN is higher than VINPOR threshold.
4	FB2	Feedback Voltage Input for Channel 2. Connect FB2 to a resistive voltage divider from VOUT2 to GND to adjust output from 2V to 4V.
5	CS2	Current Limit Setting. Connect a resistor to GND to set the threshold for Channel 2 synchronous $R_{DS(ON)}$ sense. The GND – PHASE2 current limit threshold is 1/8th the voltage seen at CS2 over a 0.2V to 2V range. There is an internal $10\mu A$ current source from LDO5 to CS2.
6	EN2	Enable Control Input for Channel 2.
7	PGOOD	Power Good Indicator Output for Channel 1 and Channel 2. (Logical AND)
8	PHASE2	Switch Node of Channel 2 MOSFETs. PHASE2 is the internal lower supply rail for the UGATE2 high-side gate driver. PHASE2 is also the current-sense input for the Channel 2.
9	воот2	Bootstrap Supply for Channel 2 High-Side Gate Driver. Connect to an external capacitor according to the typical application circuits.
10	UGATE2	High-Side Gate Driver Output for Channel 2. UGATE2 swings between PHASE2 and BOOT2.
11	LGATE2	Low-Side Gate Driver Output for Channel 2. LGATE2 swings between GND and LDO5.
12	VIN	Power Input for 5V and 3.3V LDO Regulators and Buck Controllers.
13	LDO5	5V Linear Regulator Output. LDO5 is also the supply voltage for the low-side MOSFET and analog supply voltage for the device.
14	BYP1	Switch-over Source Voltage Input for LDO5.
15	LGATE1	Low-Side Gate Driver Output for Channel 1. LGATE1 swings between GND and LDO5.
16	UGATE1	High-Side Gate Driver Output for Channel 1. UGATE1 swings between PHASE1 and BOOT1.
17	BOOT1	Bootstrap Supply for Channel 1 High-Side Gate Driver. Connect to an external capacitor according to the typical application circuits.
18	PHASE1	Switch Node of Channel 1 MOSFETs. PHASE1 is the internal lower supply rail for the UGATE1 high-side gate driver. PHASE1 is also the current sense input for the Channel 1.
19	VCLK	Oscillator Output for Charge Pump.
20	EN1	Enable Control Input for Channel 1.
21 (Exposed Pad)	GND	Ground. The exposed pad must be soldered to a large PCB and connected to GND for maximum power dissipation.



Functional Block Diagram



Operation

The RT6575C/D includes two constant on-time synchronous step-down controllers and two linear regulators.

Buck Controller

In normal operation, the high-side N-MOSFET is turned on when the output is lower than VREF, and is turned off after the internal one-shot timer expires. While the highside N-MOSFET is turned off, the low-side N-MOSFET is turned on to conduct the inductor current until next cycle begins.

Soft-Start

For internal soft-start function, an internal current source charges an internal capacitor to build the soft-start ramp voltage. The output voltage will track the internal ramp voltage during soft-start interval.

PGOOD

The power good output is an open-drain architecture. When the two channels soft-start are both finished, the PGOOD open-drain output will be high impedance.

Current Limit

The current limit circuit employs a unique "valley" current sensing algorithm. If the magnitude of the current sense signal at PHASE is above the current limit threshold, the PWM is not allowed to initiate a new cycle. Thus, the current to the load exceeds the average output inductor current, the output voltage falls and eventually crosses the under-voltage protection threshold, inducing IC shutdown.

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Over-Voltage Protection (OVP) & Under-Voltage Protection (UVP)

The two channel output voltages are continuously monitored for over-voltage and under-voltage conditions. When the output voltage exceeds over-voltage threshold (113% of VOUT), UGATE goes low and LGATE is forced high. When it is less than 52% of reference voltage, under-voltage protection is triggered and then both UGATE and LGATE gate drivers are forced low. The controller is latched until ENx is reset or LDO5 is re-supplied.

LDO5 and LDO3

When the VIN voltage exceeds the POR rising threshold, LDO3 will default turn-on. The LDO5 can be power on by ENx. The linear regulator LDO5 and LDO3 provide 5V and 3.3V regulated output.

Switching Over

The BYP1 is connected to the Channel 1 output. After the Channel 1 output voltage exceeds the set threshold (4.66V), the output will be bypassed to the LDO5 output to maximize the efficiency.



Absolute Maximum Ratings (Note 1)	
• VIN to GND	-0.3V to 30V
BOOTx to GND	
DC	-0.3V to 36V
<100ns	
BOOTx to PHASEx	
DC	-0.3V to 6V
<100ns	
PHASEx to GND	
DC	-5V to 30V
<100ns	-10V to 42V
UGATEx to GND	
DC	-5V to 36V
<100ns	-10V to 42V
UGATEx to PHASEx	
DC	-0.3V to 6V
<100ns	-5V to 7.5V
LGATEx to GND	
DC	-0.3V to 6V
<100ns	-5V to 7.5V
• Other Pins	-0.3V to 6.5V
 Power Dissipation, P_D @ T_A = 25°C 	
WQFN-20L 3x3	3.33W
Package Thermal Resistance (Note 2)	
WQFN-20L 3x3, θ _{JA}	30°C/W
WQFN-20L 3x3, θ_{JC}	7.5°C/W
• Junction Temperature	150°C
• Lead Temperature (Soldering, 10 sec.)	260°C
Storage Temperature Range	-65°C to 150°C
ESD Susceptibility (Note 3)	
HBM (Human Body Model)	2kV
Recommended Operating Conditions (Note 4)	
• Supply Voltage, VIN	5V to 25V
• Junction Temperature Range	
Ambient Temperature Range	



Electrical Characteristics

 $(V_{IN} = 12V, V_{EN1} = V_{EN2} = 3.3V, V_{CS1} = V_{CS2} = 2V, No Load, T_A = 25$ °C, unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit		
Input Supply								
VIN Davier On Daget	VAN	Rising Threshold		4.6	4.9			
VIN Power-On Reset	VIN _{POR}	Falling Threshold 3.2 3		3.7		V		
VIN Standby Supply Current	I	RT6575C Both Buck Controllers Off, V _{EN1} = V _{EN2} = GND		60	80			
VIN Standby Supply Current	IVIN_SBY	RT6575D Both Buck Controllers Off, V _{EN1} = V _{EN2} = GND		80	100	- μΑ		
VIN Quiescent Current	I _{VIN_nosw}	Both Buck Controllers On, V _{FBx} = 2.05V, V _{BYP1} = 5.05V		15	25	μА		
BYP1 Supply Current	I _{BYP1_nosw}	Both Buck Controllers On, V _{FBx} = 2.05V, V _{BYP1} = 5.05V		420	500	μА		
Buck Controllers Output and	d FB Voltage							
FBx Valley Trip Voltage	V _{FBx}	CCM Operation	1.98	2	2.02	V		
BYP1 Discharge Current	IDCHG_BYP1	V _{BYP1} = 0.5V	10	45		mA		
PHASEx Discharge Current	I _{DCHG_LX}	V _{PHASEx} = 0.5V	5	8		mA		
Switching Frequency								
Switching Fraguency	fswx	V _{IN} = 20V, V _{OUT1} = 5V	240	300	360	kHz		
Switching Frequency		V _{IN} = 20V, V _{OUT2} = 3.33V	280	355	430			
Minimum Off-Time	toff(MIN)	V _{FBx} = 1.9V		200	275	ns		
Soft-Start								
Soft-Start Time	t _{SSx}	V _{OUTx} Ramp-up Time		0.9		ms		
Current Sense								
CSx Source Current	I _{CSx}	$V_{CSx} = 1V$, $V_{FBx} = 1.9V$	9	10	11	μΑ		
CSx Current Temperature Coefficient	TC _{ICSx}	In Comparison with 25°C		4700		ppm/°C		
Zero-Current Threshold	V _{ZC}	V _{FBx} = 2.05V, GND – PHASEx		1		mV		
Internal Regulator								
		V _{IN} = 12V, No Load	4.9	5	5.1			
LDO5 Output Voltage	V _{LDO5}	V _{IN} > 7V, I _{LDO5} < 100mA	4.8	5	5.1	V		
LDO3 Output Voltage	VLDO5	V _{IN} > 5.5V, I _{LDO5} < 35mA	4.8	5	5.1] ^v		
		V _{IN} > 5V, I _{LDO5} < 20mA	4.5	4.75	5.1			
		V _{IN} = 12V, No Load	3.267	3.3	3.333			
LDO2 Output Voltage	Vipos	V _{IN} > 7V, I _{LDO3} < 100mA	3.217	3.3	3.383			
LDO3 Output Voltage	V _{LDO3}	V _{IN} > 5.5V, I _{LDO3} < 35mA	3.267	3.3	3.333	<u> </u>		
		V _{IN} > 5V, I _{LDO3} < 20mA	3.217	3.3	3.383			



Paramet	Parameter		Test Conditions	Min	Тур	Max	Unit
LDO5 Output Cu	rrent	I _{LDO5}	$V_{LDO5} = 4.5V$, $V_{BYP1} = GND$, $V_{IN} = 7.4V$		175		mA
LDO3 Output Current		I _{LDO3}	V _{LDO3} = 3V, V _{IN} = 7.4V	100	175	-	mA
LDO5 Switch-ove Threshold to BYI		VswTH	Rising Edge at BYP1 Regulation Point		4.66		V
LDO5 Switch-ove Equivalent Resis		Rsw	LDO5 to BYP1, 10mA		1.5	3	Ω
VCLK Output							
VCLK On-Resist	ance	Rvclk	Pull-up and Pull-down Resistance		10	-	Ω
VCLK Switching Frequency		f _{VCLK}			260	-	kHz
UVLO							
LDO5 UVLO Thr	rechold	V _{UVLO5}	Rising Edge		4.3	4.6	V
LDOS OVLO IIII	esiloid	VUVLO5	Falling Edge	3.7	3.9	4.1	7
LDO3 UVLO Thr	eshold	V _{UVLO3}	Channel x Off		2.5		V
Power Good Inc	dicator						
PGOOD Thresho	al d	V _{PGxTH}	PGOOD Detect, VFBx Rising Edge	84 88 92		92	<u> </u> %
PGOOD Thresho	old		Hysteresis		8		70
PGOOD Leakag	e Current		High state, V _{PGOOD} = 5.5V			1	μА
PGOOD Output Low Voltage			ISINK = 4mA			0.3	٧
PGOOD Delay Time			From Soft-start End to PGOOD High		0.75		ms
Fault Detection		•					
OVP Trip Thresh	old	V _{OVP}	FBx with Respect to Internal Reference	109	113	117	%
OVP Propagation	n Delay				1		μS
UVP Trip Thresh	old	Vuvp	UVP Detect, FBx Falling Edge	47	52	57	%
UVP Shutdown E	Blanking	t _{SHDN_UVP}	From ENx Enable		1.3		ms
Thermal Shutdo	own	•					
Thermal Shutdov	wn	T _{SD}			150		°C
Thermal Shutdown Hysteresis		ΔT _{SD}			10		°C
Logic Inputs					1		
	ogic-High	V _{ENx_H}	SMPS On	1.6			
Thershold Voltage Logic-Low		V _{ENx_L}	SMPS Off			0.4	V
Internal Boost S	Internal Boost Switch						
Internal Boost St Resistance	witch On-	R _{BST}	LDO5 to BOOTx		80		Ω

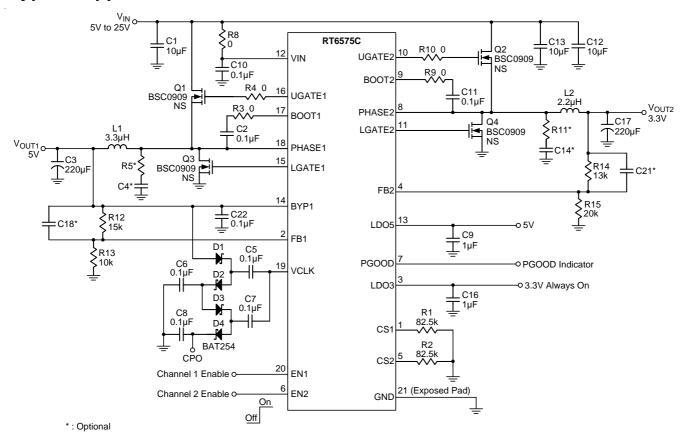


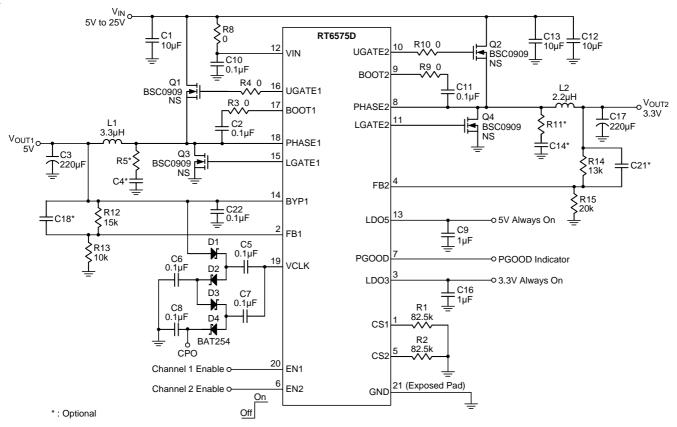
Parameter	Symbol	mbol Test Conditions		Тур	Max	Unit
Power MOSFET Drivers						
UGATEx On-Resistance	Pugare	High State, $V_{BOOTx} - V_{UGATEx} = 0.25V$, $V_{BOOTx} - V_{PHASEx} = 5V$		3		Ω
OGATEX Off-Resistance	RUGATEX	Low State, V _{UGATEX} - V _{PAHSEX} = 0.25V, V _{BOOTX} - V _{PHASEX} = 5V	1	2	-	52
LGATEx On-Resistance	RLGATEX	High State, V _{LDO5} – V _{LGATEx} = 0.25V, V _{LDO5} = 5V		3	1	Ω
		Low State, $V_{LGATEx} - GND = 0.25V$		1		
Dood Time	4-	LGATEx Rising		20		20
Dead-Time	tD	UGATEx Rising		30		ns

- **Note 1.** Stresses beyond those listed "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.
- Note 2. θ_{JA} is measured at $T_A = 25^{\circ}C$ on a high effective thermal conductivity four-layer test board per JEDEC 51-7. θ_{JC} is measured at the exposed pad of the package.
- Note 3. Devices are ESD sensitive. Handling precaution is recommended.
- Note 4. The device is not guaranteed to function outside its operating conditions.



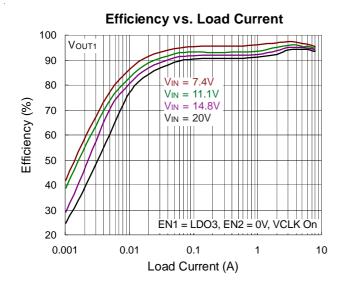
Typical Application Circuit

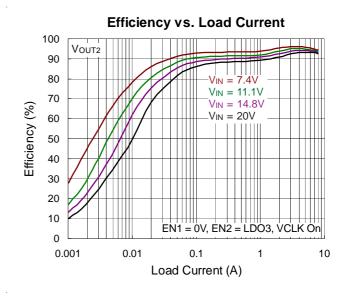


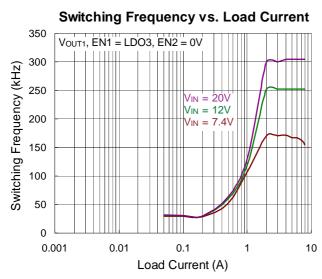


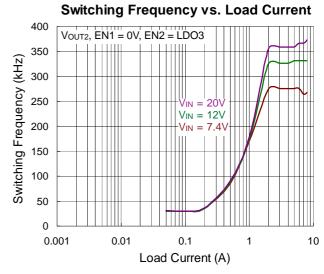


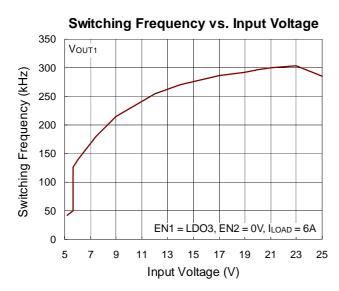
Typical Operating Characteristics

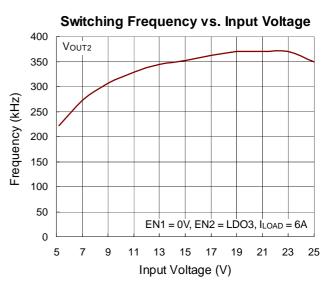




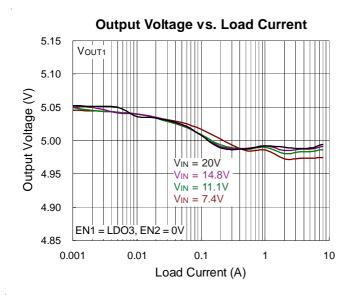


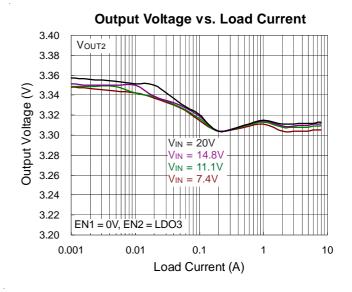


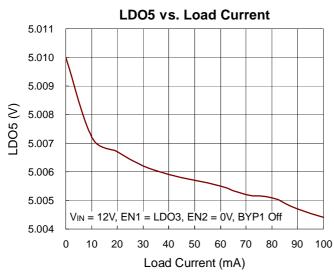


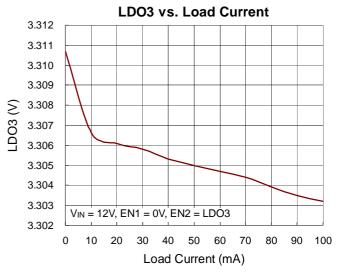


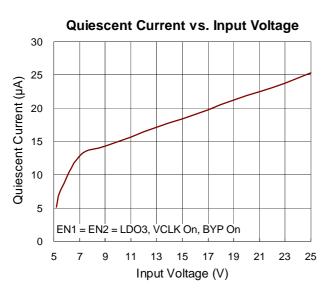


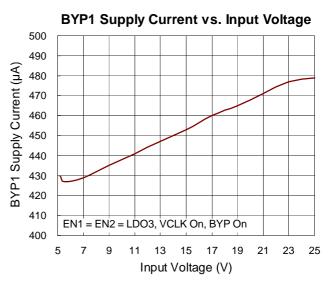




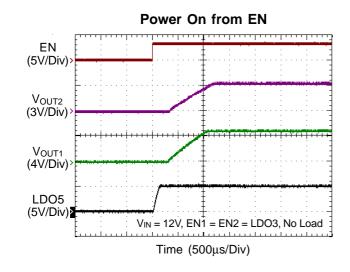


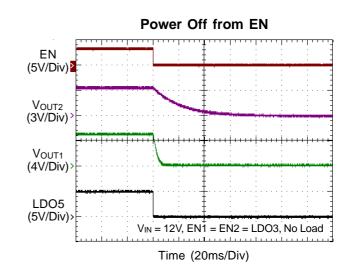


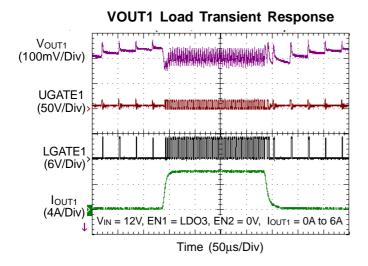


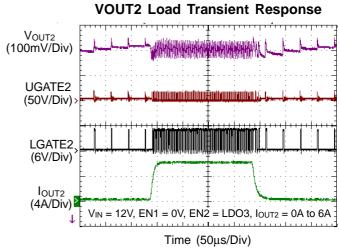


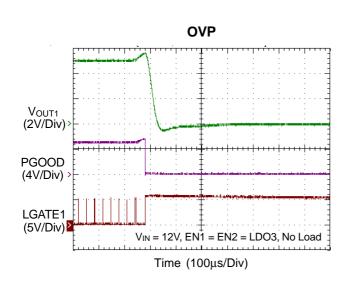


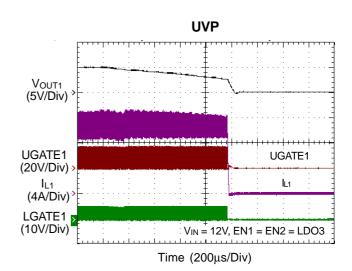














Application Information

The RT6575C/D is a dual-channel, low quiescent, Mach ResponseTM DRVTM mode synchronous Buck controller targeted for Ultrabook system power supply solutions. Richtek's Mach ResponseTM technology provides fast response to load steps. The topology solves the poor load transient response timing problems of fixed frequency current mode PWMs, and avoids the problems caused by widely varying switching frequencies in CCR (constant current ripple) constant on-time and constant off-time PWM schemes. A special adaptive on-time control trades off the performance and efficiency over wide input voltage range. The RT6575C/D includes 5V (LDO5) and 3.3V (LDO3) linear regulators. The LDO5 linear regulator steps down the battery voltage to supply both internal circuitry and gate drivers. The synchronous switch gate drivers are directly powered by LDO5. When V_{OUT1} rises above 4.66V, an automatic circuit disconnects the linear regulator and allows the device to be powered by V_{OUT1} via the BYP1 pin.

PWM Operation

The Mach ResponseTM DRVTM mode controller relies on the output filter capacitor's Effective Series Resistance (ESR) to act as a current sense resistor, so that the output ripple voltage provides the PWM ramp signal. Referring to the RT6575C/D's Function Block Diagram, the synchronous high-side MOSFET is turned on at the beginning of each cycle. After the internal one-shot timer expires, the MOSFET will be turned off. The pulse width of this one-shot is determined by the converter's input output voltages to keep the frequency fairly constant over the entire input voltage range. Another one-shot sets a minimum off-time (200ns typ.). The on-time one-shot will be triggered if the error comparator is high, the low-side switch current is below the current limit threshold, and the minimum off-time one-shot has timed out.

PWM Frequency and On-time Control

For each specific input voltage range, the Mach ResponseTM control architecture runs with pseudo constant frequency by feed forwarding the input and output voltage into the on-time one-shot timer. The high-side switch on-time is inversely proportional to the input voltage as measured by V_{IN} and proportional to the output voltage. The inductor ripple current operating point remains relatively constant, resulting in easy design methodology and predictable output voltage ripple. The frequency of 3V output controller is set higher than the frequency of 5V output controller. This is done to prevent audio frequency "beating" between the two sides, which switch asynchronously for each side.

The RT6575C/D adaptively changes the operation frequency according to the input voltage. Higher input voltage usually comes from an external adapter, so the RT6575C/D operates with higher frequency to have better performance. Lower input voltage usually comes from a battery, so the RT6575C/D operates with lower switching frequency for lower switching losses. For a specific input voltage range, the switching cycle period is given by :

For 5V VOUT,

Period (sec.) =
$$\frac{V_{IN} \times 2.7 \times 10^{-6}}{V_{IN} - 3.79}$$

For 3.3V VOUT,
Period (sec.) =
$$\frac{V_{IN} \times 2.45 \times 10^{-6}}{V_{IN} - 2.59}$$

where the VIN is in volt.

The on-time guaranteed in the Electrical Characteristics table is influenced by switching delays in the external high-side power MOSFET.

Diode Emulation Mode

In diode emulation mode, the RT6575C/D automatically reduces switching frequency at light load conditions to maintain high efficiency. This reduction of frequency is achieved smoothly. As the output current decreases from heavy load condition, the inductor current is also reduced, and eventually comes to the point that its current valley touches zero, which is the boundary between continuous conduction and discontinuous conduction modes. To emulate the behavior of diodes, the low-side MOSFET allows only partial negative current to flow when the inductor free wheeling current becomes negative. As the load current is further decreased, it takes longer and longer

time to discharge the output capacitor to the level that requires the next "ON" cycle. The on-time is kept the same as that in the heavy load condition. In reverse, when the output current increases from light load to heavy load, the switching frequency increases to the preset value as the inductor current reaches the continuous conduction. The transition load point to the light load operation is shown in Figure 1. and can be calculated as follows:

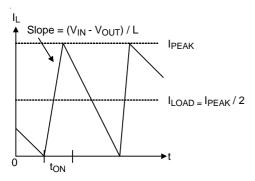


Figure 1. Boundary Condition of CCM/DEM

$$I_{LOAD(SKIP)} \approx \frac{(V_{IN} - V_{OUT})}{2L} \times t_{ON}$$

where toN is the on-time.

The switching waveforms may appear noisy and asynchronous when light load causes diode emulation operation. This is normal and results in high efficiency. Trade offs in PFM noise vs. light load efficiency is made by varying the inductor value. Generally, low inductor values produce a broader efficiency vs. load curve, while higher values result in higher full load efficiency (assuming that the coil resistance remains fixed) and less output voltage ripple. Penalties for using higher inductor values include larger physical size and degraded load transient response (especially at low input voltage levels).

Ultrasonic Mode (ASM)

The RT6575C/D activates a unique type of diode emulation mode with a minimum switching frequency of 25kHz, called ultrasonic mode. This mode eliminates audiofrequency modulation that would otherwise be present when a lightly loaded controller automatically skips pulses. In ultrasonic mode, the low-side switch gate driver signal is "OR"ed with an internal oscillator (>25kHz). Once the internal oscillator is triggered, the controller will turn on UGATE and give it shorter on-time.

When the on-time expired, LGATE turns on until the inductor current goes to zero crossing threshold and keep both high-side and low-side MOSFET off to wait for the next trigger. Because shorter on-time causes a smaller pulse of the inductor current, the controller can keep output voltage and switching frequency simultaneously. The ontime decreasing has a limitation and the output voltage will be lifted up under the slight load condition. The controller will turn on LGATE first to pull down the output voltage. When the output voltage is pulled down to the balance point of the output load current, the controller will proceed the short on-time sequence as the above description.

Linear Regulators (LDOx)

The RT6575C/D includes 5V (LDO5) and 3.3V (LDO3) linear regulators. The regulators can supply up to 100mA for external loads. Bypass LDOx with a $1\mu F$ to $4.7\mu F$, and recommended value is $1\mu F$ ceramic capacitor. When V_{OUT1} is higher than the switch over threshold (4.66V), an internal 1.5Ω P-MOSFET switch connects BYP1 to the LDO5 pin while simultaneously disconnects the internal linear regulator.

Current Limit Setting

The RT6575C/D has cycle-by-cycle current limit control. The current limit circuit employs a unique "valley" current sensing algorithm. If the magnitude of the current sense signal at PHASEx is above the current limit threshold, the PWM is not allowed to initiate a new cycle (Figure 2). The actual peak current is greater than the current limit threshold by an amount equal to the inductor ripple current. Therefore, the exact current limit characteristic and maximum load capability are a function of the sense resistance, inductor value, battery and output voltage.

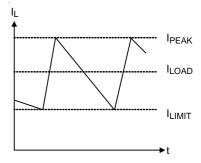


Figure 2. "Valley" Current Limit

The RT6575C/D uses the on resistance of the synchronous rectifier as the current sense element and supports temperature compensated MOSFET R_{DS(ON)} sensing. The R_{ILIM} resistor between the CSx pin and GND sets the current limit threshold. The resistor R_{ILIM} is connected to a current source from CSx which is 10μA (typ.) at room temperature. The current source has a 4700ppm/°C temperature slope to compensate the temperature dependency of the R_{DS(ON)}. When the voltage drop across the sense resistor or low-side MOSFET equals 1/8 the voltage across the R_{ILIM} resistor, positive current limit will be activated. The high-side MOSFET will not be turned on until the voltage drop across the MOSFET falls below 1/8 the voltage across the R_{ILIM} resistor.

Choose a current limit resistor according to the following equation:

$$V_{LIMIT} = (R_{LIMIT} \times 10 \mu A) / 8 = I_{LIMIT} \times R_{DS(ON)}$$

$$R_{LIMIT} = (I_{LIMIT} x R_{DS(ON)}) x 8 / 10 \mu A$$

Carefully observe the PC board layout guidelines to ensure that noise and DC errors do not corrupt the current sense signal at PHASEx and GND. Mount or place the IC close to the low-side MOSFET.

VCLK for Charge Pump

A 260kHz VCLK signal can be used for the external charge pump circuit. The VCLK signal becomes available when EN1 enters ON state. VCLK driver circuit is driven by BYP1 voltage.

The external 14V charge pump is driven by VCLK. As shown in Figure 3, when VCLK is low, C1 will be charged by V_{OUT1} through D1. C1 voltage is equal to V_{OUT1} minus the diode drop. When VCLK becomes high, C1 transfers the charge to C2 through D2 and charges C2 voltage to V_{VCLK} plus C1 voltage. As VCLK transitions low on the next cycle, C3 is charged to C2 voltage minus a diode drop through D3. Finally, C3 charges C4 through D4 when VCLK switches high. Thus, the total charge pump voltage, V_{CP}, is:

$$V_{CP} = V_{OUT1} + 2 \times V_{VCLK} - 4 \times V_{D}$$

where V_{VCLK} is the peak voltage of the VCLK driver which is equal to LDO5 and V_D is the forward voltage dropped across the Schottky diode.

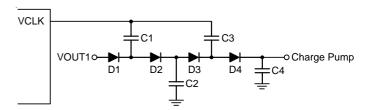


Figure 3. Charge Pump Circuit Connected to VCLK

MOSFET Gate Driver (UGATEx, LGATEx)

The high-side driver is designed to drive high current, low R_{DS(ON)} N-MOSFET(s). When configured as a floating driver, 5V bias voltage is delivered from the LDO5 supply. The average drive current is also calculated by the gate charge at $V_{GS} = 5V$ times switching frequency. The instantaneous drive current is supplied by the flying capacitor between the BOOTx and PHASEx pins. A dead-time to prevent shoot through is internally generated from high-side MOSFET off to low-side MOSFET on and low-side MOSFET off to high-side MOSFET on.

The low-side driver is designed to drive high current low R_{DS(ON)} N-MOSFET(s). The internal pull down transistor that drives LGATEx low is robust, with a 1Ω typical onresistance. A 5V bias voltage is delivered from the LDO5 supply. The instantaneous drive current is supplied by an input capacitor connected between LDO5 and GND.

For high current applications, some combinations of high and low-side MOSFETs may cause excessive gate drain coupling, which leads to efficiency killing, EMI producing, and shoot through currents. This is often remedied by adding a resistor in series with BOOTx, which increases the turn-on time of the high-side MOSFET without degrading the turn-off time. See Figure 4.

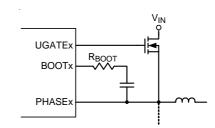


Figure 4. Increasing the UGATEx Rise Time



Soft-Start

The RT6575C/D provides an internal soft-start function to prevent large inrush current and output voltage overshoot when the converter starts up. The soft-start (SS) automatically begins once the chip is enabled. During soft-start, it clamps the ramping of internal reference voltage which is compared with FBx signal. The typical soft-start duration is 0.9ms. A unique PWM duty limit control that prevents output over-voltage during soft-start period is designed specifically for FBx floating.

UVLO Protection

The RT6575C/D has LDO5 under-voltage lock out protection (UVLO). When the LDO5 voltage is lower than 3.9V (typ.) and the LDO3 voltage is lower than 2.5V (typ.), both switch power supplies are shut off. This is a non-latch protection.

Power Good Output (PGOOD)

PGOOD is an open-drain output and requires a pull-up resistor. PGOOD is actively held low in soft-start, standby, and shutdown. For RT6575C/D, PGOOD is released when both output voltages are above 88% of nominal regulation point. The PGOOD signal goes low if either output turns off or is 20% below or 13% over its nominal regulation point.

Output Over-Voltage Protection (OVP)

The output voltage can be continuously monitored for overvoltage condition. If the output voltage exceeds 13% of its set voltage threshold, the over-voltage protection is triggered and the LGATEx low-side gate drivers are forced high. This activates the low-side MOSFET switch, which rapidly discharges the output capacitor and pulls the output voltage downward.

The RT6575C/D is latched once OVP is triggered and can only be released by either toggling ENx or cycling VIN. There is a $1\mu s$ delay built into the over-voltage protection circuit to prevent false transition.

Note that latching LGATEx high will cause the output voltage to dip slightly negative due to previously stored energy in the LC tank circuit. For loads that cannot tolerate a negative voltage, place a power Schottky diode across the output to act as a reverse polarity clamp.

If the over-voltage condition is caused by a shorted in high-side switch, turning the low-side MOSFET on 100% will create an electrical shorted circuit between the battery and GND to blow the fuse and disconnecting the battery from the output.

Output Under-Voltage Protection (UVP)

The output voltage can be continuously monitored for undervoltage condition. If the output is less than 52% (typ.) of its set voltage threshold, the under-voltage protection will be triggered and then both UGATEx and LGATEx gate drivers will be forced low. The UVP is ignored for at least 1.3ms (typ.) after a start-up or a rising edge on ENx. Toggle ENx or cycle VIN to reset the UVP fault latch and restart the controller.

Thermal Protection

The RT6575C/D features thermal shutdown to prevent damage from excessive heat dissipation. Thermal shutdown occurs when the die temperature exceeds 150°C. All internal circuitries are turned off during thermal shutdown. The RT6575C/D triggers thermal shutdown if LDO5 is not supplied from V_{OUT1}, while input voltage on VIN and drawing current from LDO5 are too high. Nevertheless, even if LDO5 is supplied from V_{OUT1}, overloading LDO5 can cause large power dissipation on automatic switches, which may still result in thermal shutdown.

Discharge Mode (Soft Discharge)

When ENx is low the output under-voltage fault latch is set, the output discharge mode will be triggered. During discharge mode, an internal switch creates a path for discharging the output capacitors' residual charge to GND.



Standby Mode

When VIN exceeds POR threshold and ENx < 0.4V, the RT6575C/D operate in standby mode, and CH1 and CH2 are OFF state. For the RT6575C, LDO5 is OFF and LDO3 is ON state and approximately consumes 15 μ A of input current. For the RT6575D, LDO5 and LDO3 are ON state and approximately consumes 25 μ A while in standby mode.

Power-Up Sequencing and On/Off Controls (ENx)

EN1 and EN2 control the power-up sequencing of the two channels of the Buck converter. The 0.4V falling edge threshold on ENx can be used to detect a specific analog voltage level and to shutdown the device. Once in shutdown, the 1.6V rising edge threshold activates, providing sufficient hysteresis for most applications.

Table 1. Operation Mode Truth Table

Mode	Condition	Comment
LDO Over Current Limit	LDOx < UVLO threshold	Transitions to discharge mode after VIN POR. LDO5 and LDO3 remain active.
Run	$ENx = high, V_{OUT1} \text{ or } V_{OUT2} \text{ are enabled}$	Normal Operation.
Over-Voltage Protection	Either output >113% of the nominal level.	LGATEx is forced high. LDO3 and LDO5 are active. Exit by VIN POR or by toggling ENx.
Under-Voltage Protection	Either output < 52% of the nominal level after 1.3ms time-out expires and output is enabled	Both UGATEx and LGATEx are forced low and enter discharge mode. LDO3 and LDO5 are active. Exit by VIN POR or by toggling ENx.
Discharge	Either output is still high in standby mode	During discharge mode, there is one path to discharge the output capacitors' residual charge to GND via an internal switch.
Standby	VIN > POR ENx < 0.4V	For RT6575C : LDO3 is active For RT6575D : LDO3, LDO5 are active
Thermal Shutdown	T _J > 150°C	All circuitries are off. Exit by VIN POR.

Table 2. Enabling/PGOOD State (RT6575C)

EN1	EN2	LDO5	LDO3	CH1 (5VOUT)	CH2 (3.3VOUT)	VCLK	PGOOD
OFF	OFF	OFF	ON	OFF	OFF	OFF	Low
ON	OFF	ON	ON	ON	OFF	ON	Low
OFF	ON	ON	ON	OFF	ON	OFF	Low
ON	ON	ON	ON	ON	ON	ON	High

Table 3. Enabling/PGOOD State (RT6575D)

EN1	EN2	LDO5	LDO3	CH1 (5VOUT)	CH2 (3.3VOUT)	VCLK	PGOOD
OFF	OFF	ON	ON	OFF	OFF	OFF	Low
ON	OFF	ON	ON	ON	OFF	ON	Low
OFF	ON	ON	ON	OFF	ON	OFF	Low
ON	ON	ON	ON	ON	ON	ON	High

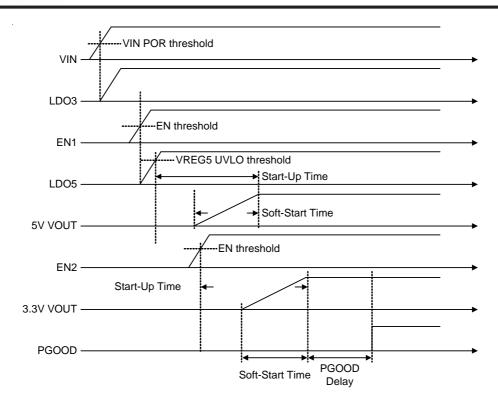


Figure 5. RT6575C Timing

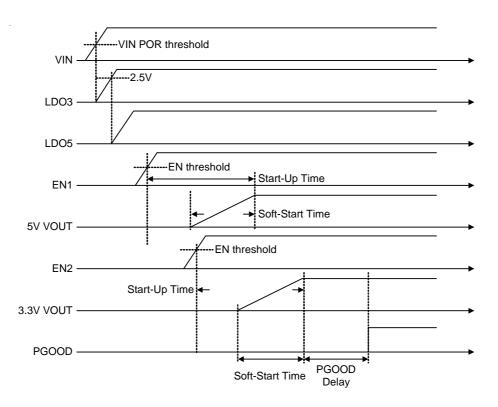


Figure 6. RT6575D Timing



Output Voltage Setting (FBx)

Connect a resistive voltage divider at the FBx pin between V_{OUTx} and GND to adjust the output voltage from 2V to 5.5V for CH1 and 2V to 4V for CH2, as shown in Figure 7. The recommended R2 value is between $10k\Omega$ to $20k\Omega$, and solve for R1 using the equation below:

$$V_{OUT(Valley)} = V_{FBx} \times \left(1 + \left(\frac{R1}{R2}\right)\right)$$

where V_{FBx} is 2V (typ.).

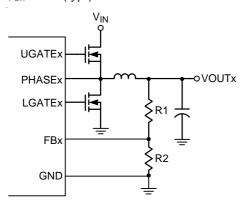


Figure 7. Setting V_{OUTx} with a resistive voltage divider

Output Inductor Selection

The switching frequency (on-time) and operating point (% ripple or LIR) determine the inductor value as shown below:

$$L = \frac{t_{ON} \times (V_{IN} - V_{OUTx})}{LIR \times I_{LOAD(MAX)}}$$

where LIR is the ratio of the peak-to-peak ripple current to the average inductor current.

Find a low-loss inductor having the lowest possible DC resistance that fits in the allotted dimensions. Ferrite cores are often the best choice, although powdered iron is inexpensive and can work well at 200kHz. The core must be large enough not to saturate at the peak inductor current, I_{PEAK}:

$$I_{PEAK} = I_{LOAD(MAX)} + [(LIR/2) \times I_{LOAD(MAX)}]$$

The calculation above shall serve as a general reference. To further improve transient response, the output inductance can be further reduced. Of course, besides the inductor, the output capacitor should also be considered when improving transient response.

Output Capacitor Selection

The capacitor value and ESR determine the amount of output voltage ripple and load transient response. Thus, the capacitor value must be greater than the largest value calculated from the equations below:

$$V_{SAG} = \frac{(\Delta I_{LOAD})^2 \times L \times (t_{ON} + t_{OFF(MIN)})}{2 \times C_{OUT} \times \left[V_{IN} \times t_{ON} - V_{OUTx}(t_{ON} + t_{OFF(MIN)}) \right]}$$

$$V_{SOAR} = \frac{(\Delta I_{LOAD})^2 \times L}{2 \times C_{OUT} \times V_{OUTx}}$$

$$V_{P-P} = LIR \times I_{LOAD(MAX)} \times \left(ESR + \frac{1}{8 \times C_{OUT} \times f}\right)$$

where V_{SAG} and V_{SOAR} are the allowable amount of undershoot and overshoot voltage during load transient, V_{p-p} is the output ripple voltage, and $t_{OFF(MIN)}$ is the minimum off-time.

Thermal Considerations

For continuous operation, do not exceed absolute maximum junction temperature. The maximum power dissipation depends on the thermal resistance of the IC package, PCB layout, rate of surrounding airflow, and difference between junction and ambient temperature. The maximum power dissipation can be calculated by the following formula:

$$P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$$

where $T_{J\left(MAX\right)}$ is the maximum junction temperature, T_{A} is the ambient temperature, and θ_{JA} is the junction to ambient thermal resistance.

For recommended operating condition specifications, the maximum junction temperature is 125°C. The junction to ambient thermal resistance, θ_{JA} , is layout dependent. For WQFN-20L 3x3 package, the thermal resistance, θ_{JA} , is 30°C/W on a standard JEDEC 51-7 four-layer thermal test board. The maximum power dissipation at $T_A = 25^{\circ}$ C can be calculated by the following formula:

 $P_{D(MAX)} = (125^{\circ}C - 25^{\circ}C) / (30^{\circ}C/W) = 3.33W$ for WQFN-20L 3x3 package

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The maximum power dissipation depends on the operating ambient temperature for fixed $T_{J(MAX)}$ and thermal resistance, θ_{JA} . The derating curve in Figure 8 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.

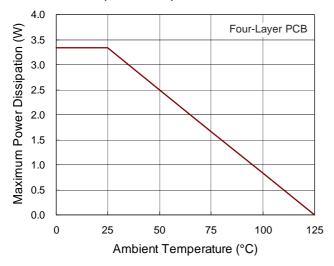


Figure 8. Derating Curve of Maximum Power Dissipation

Layout Considerations

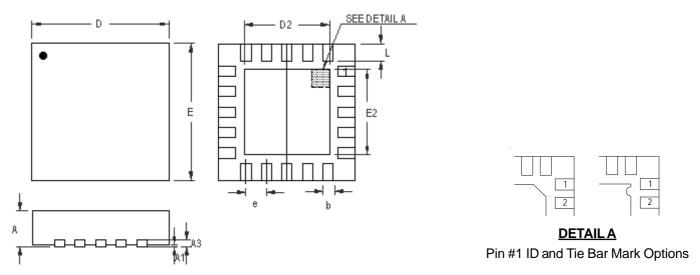
Layout is very important in high frequency switching converter design. Improper PCB layout can radiate excessive noise and contribute to the converter's instability. Certain points must be considered before starting a layout with the RT6575C/D.

- ▶ Place the filter capacitor close to the IC, within 12mm (0.5 inch) if possible.
- Keep current limit setting network as close as possible to the IC. Routing of the network should avoid coupling to high-voltage switching node.
- Connections from the drivers to the respective gate of the high-side or the low-side MOSFET should be as short as possible to reduce stray inductance. Use 0.65mm (25 mils) or wider trace.
- All sensitive analog traces and components such as FBx, PGOOD, and should be placed away from high voltage switching nodes such as PHASEx, LGATEx, UGATEx, or BOOTx nodes to avoid coupling. Use internal layer(s) as ground plane(s) and shield the feedback trace from power traces and components.
- ▶ Place ground terminal of VIN capacitor(s), V_{OUTx} capacitor(s), and Source of low-side MOSFETs as close to each other as possible. The PCB trace of PHASEx node, which connects to Source of high-side MOSFET, Drain of low-side MOSFET and high voltage side of the inductor, should be as short and wide as possible.

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Outline Dimension



Note: The configuration of the Pin #1 identifier is optional, but must be located within the zone indicated.

Symbol	Dimensions	In Millimeters	Dimensions In Inches		
	Min	Max	Min	Max	
Α	0.700	0.800	0.028	0.031	
A1	0.000	0.050	0.000	0.002	
А3	0.175	0.250	0.007	0.010	
b	0.150	0.250	0.006	0.010	
D	2.900	3.100	0.114	0.122	
D2	1.650	1.750	0.065	0.069	
Е	2.900	3.100	0.114	0.122	
E2	1.650	1.750	0.065	0.069	
е	0.4	100	0.0)16	
L	0.350	0.450	0.014	0.018	

W-Type 20L QFN 3x3 Package

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